

## Lecture 5

15-1

Often of importance is the intersection of surfaces. The result is generically a curve (e.g., the intersection of two planes is a line, as we know). It is important to be able to quantify these "curves of intersection" by parametrizing them (finding a vector-valued function whose image is the curve).

Ex: Find a vector function representing the intersection of  $z = x^2$  and  $x^2 + y^2 = 4$ .

Sol: We know that whatever the vector function  $\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$  is, it must satisfy the equations of the surfaces since it lies on both of them, that is, we must have

$$z(t) = [x(t)]^2 \text{ and } [x(t)]^2 + [y(t)]^2 = 4.$$

The second equation suggests taking

$$x(t) = 2\cos t \text{ \& } y(t) = 2\sin t$$

and the first then gives  $z(t) = 4\cos^2 t$ .

Thus the vector equation is

$$\vec{r}(t) = \langle 2\cos t, 2\sin t, 4\cos^2 t \rangle$$

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## 13.2 - Derivatives and Integrals

What were the main applications of limits back in Calc I?  
Differentiation and integration!

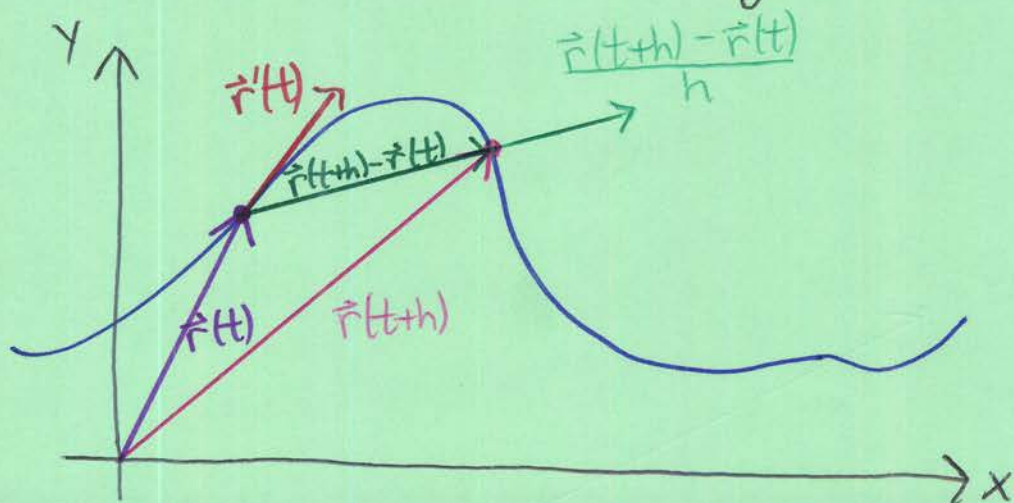
Def: The derivative of a vector function  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$

is:

$$\frac{d\vec{r}}{dt} = \vec{r}'(t) = \lim_{h \rightarrow 0} \frac{\vec{r}(t+h) - \vec{r}(t)}{h}$$

$$= \langle f'(t), g'(t), h'(t) \rangle$$

Recall that the derivative of a function gave us the slope of its tangent line. For vector-valued functions, the derivative gives us a tangent vector (pointing in the direction of increasing  $t$ -values). This vector can be used as a direction vector for the tangent line.



$\vec{r}'(a)$  is thus the tangent vector to  $\vec{r}(t)$  at  $t=a$  (provided  $\vec{r}'(a) \neq \vec{0}$ ). A very important variation of the tangent vector is the unit tangent vector:

$$\vec{T}(t) := \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}$$

This will be important in the next section.

Ex: Let  $\vec{r}(t) = \langle t \cos t, t, t \sin t \rangle$ . Find:

i)  $\vec{r}'(t)$ , ii)  $\vec{T}(t)$ , iii) an equation for the tangent line to  $\vec{r}(t)$  at  $t=\pi$ .

Sol: i)  $\vec{r}'(t) = \langle \cos t - t \sin t, 1, \sin t + t \cos t \rangle$

ii) First, we need  $\|\vec{r}'(t)\|$ :

$$\begin{aligned} \|\vec{r}'(t)\| &= \sqrt{(\cos t - t \sin t)^2 + 1 + (\sin t + t \cos t)^2} \\ &= \sqrt{\cos^2 t - 2t \cos t \sin t + t^2 \sin^2 t + 1 + \sin^2 t + 2t \sin t \cos t + t^2 \cos^2 t} \\ &= \sqrt{1 + t^2 + 1} = \sqrt{t^2 + 2} \end{aligned}$$

So, 
$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} = \frac{1}{\sqrt{t^2 + 2}} \langle \cos t - t \sin t, 1, \sin t + t \cos t \rangle$$

iii) A direction vector for the tangent line at  $t = \pi$  is

$$\vec{r}'(\pi) = \langle \cos \pi - \pi \sin \pi, 1, \sin \pi + \pi \cos \pi \rangle = \langle -1, 1, -\pi \rangle$$

(note that we could have also used  $\vec{T}(\pi)$ )

A point on the tangent line is  $\vec{r}(\pi) = \langle -\pi, \pi, 0 \rangle$ , so an equation for the tangent line is:

$$\vec{l}(s) = \vec{r}(\pi) + s \vec{r}'(\pi) = \langle -\pi - s, \pi + s, -\pi s \rangle$$



Properties of Derivatives:  $\vec{u}(t), \vec{v}(t)$ : vector functions  
 $c$  constant,  $f(t)$  scalar function

$$1) \frac{d}{dt} [\vec{u}(t) + \vec{v}(t)] = \vec{u}'(t) + \vec{v}'(t)$$

$$2) \frac{d}{dt} [c\vec{u}(t)] = c\vec{u}'(t)$$

$$3) \frac{d}{dt} [f(t)\vec{u}(t)] = f'(t)\vec{u}(t) + f(t)\vec{u}'(t)$$

$$4) \frac{d}{dt} [\vec{u}(t) \cdot \vec{v}(t)] = \vec{u}'(t) \cdot \vec{v}(t) + \vec{u}(t) \cdot \vec{v}'(t)$$

$$5) \frac{d}{dt} [\vec{u}(t) \times \vec{v}(t)] = \vec{u}'(t) \times \vec{v}(t) + \vec{u}(t) \times \vec{v}'(t)$$

$$6) \frac{d}{dt} [\vec{u}(f(t))] = \vec{u}'(f(t))f'(t)$$

} linearity of  $\frac{d}{dt}$

} Product rule

} Chain rule

There is a useful consequence of #4: Suppose  $\vec{r}'(t) \neq \vec{0}$

$$\begin{aligned} \frac{d}{dt} \|\vec{r}(t)\| &= \frac{d}{dt} \sqrt{\vec{r}(t) \cdot \vec{r}(t)} = \frac{1}{2} \frac{\frac{d}{dt} [\vec{r}(t) \cdot \vec{r}(t)]}{\sqrt{\vec{r}(t) \cdot \vec{r}(t)}} \\ &= \frac{1}{2} \frac{2\vec{r}(t) \cdot \vec{r}'(t)}{\|\vec{r}(t)\|} = \frac{\vec{r}(t) \cdot \vec{r}'(t)}{\|\vec{r}(t)\|} \end{aligned}$$


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Finally, integration:

Def: The definite integral of  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$  is

$$\begin{aligned} \int_a^b \vec{r}(t) dt &= \lim_{n \rightarrow \infty} \sum_{i=1}^n \vec{r}(t_i^*) \Delta t_i \\ &= \left\langle \int_a^b f(t) dt, \int_a^b g(t) dt, \int_a^b h(t) dt \right\rangle \end{aligned}$$

The  $t_i^*$  are chosen from the  $i^{\text{th}}$  piece of a partition of  $[a, b]$  into  $n$  pieces. One can also define indefinite

integrals:  $\int \vec{r}(t) dt = \left( \int f(t) dt \right) \hat{i} + \left( \int g(t) dt \right) \hat{j} + \left( \int h(t) dt \right) \hat{k}$

Ex: Find  $\int \vec{r}(t) dt$  and  $\int_0^2 \vec{r}(t) dt$  where  $\vec{r}(t) = t\hat{i} - t^3\hat{k}$ .

Sol:  $\int \vec{r}(t) dt = \left( \int t dt \right) \hat{i} + \left( \int 0 dt \right) \hat{j} + \left( \int -t^3 dt \right) \hat{k}$   
 $= \left( \frac{1}{2} t^2 + c_1 \right) \hat{i} + c_2 \hat{j} + \left( -\frac{1}{4} t^4 + c_3 \right) \hat{k}$

$\int_0^2 \vec{r}(t) dt = \left( \frac{1}{2} t^2 \Big|_0^2 \right) \hat{i} + 0 \hat{j} + \left( -\frac{1}{4} t^4 \Big|_0^2 \right) \hat{k} = 2\hat{i} - 4\hat{k}$

